Cytron Technologies

User's Manual

V1.0

May 2013

1.0 INTRODUCTION

The HC-SR04 ultrasonic sensor uses sonar to determine distance to an object like bats or dolphins do. It offers excellent non-contact range detection with high accuracy and stable readings in an easy-to-use package. From 2cm to 400 cm or 1" to 13 feet. It operation is not affected by sunlightor black material like Sharp rangefinders are (although acoustically soft materials like cloth can be difficult to detect). It comes complete with ultrasonic transmitter and receiver module.

Features :

● Power Supply :+5V DC
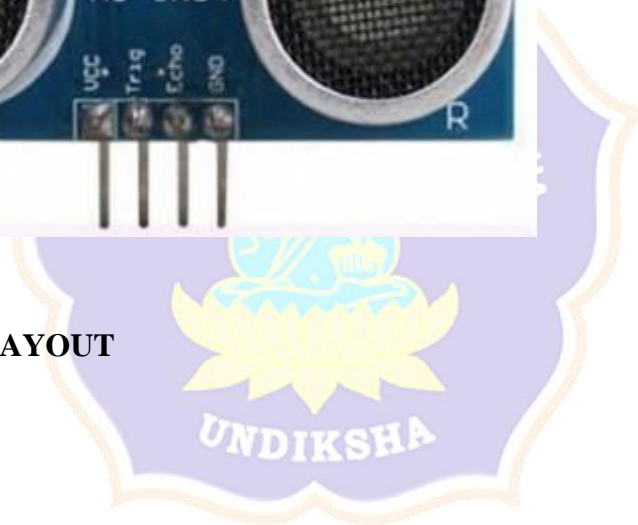
● Quiescent Current : <2Ma

● Working Currnt: 15Ma

● Effectual Angle: <15°

● Ranging Distance : 2cm – 400 cm/1" - 13ft

● Resolution : 0.3 cm

● Measuring Angle: 30 degree

● Trigger Input Pulse width: 10Us
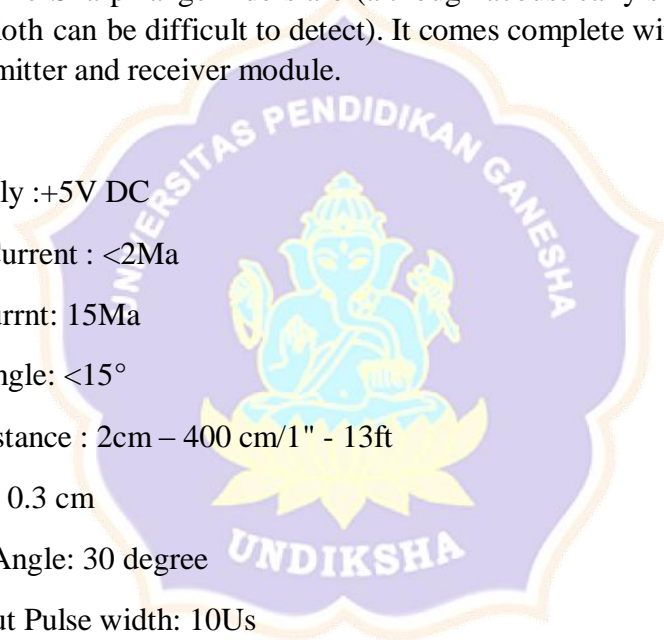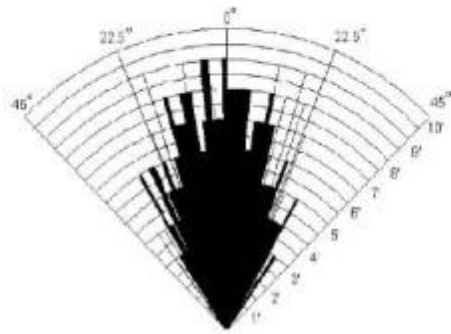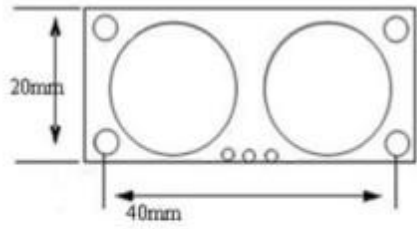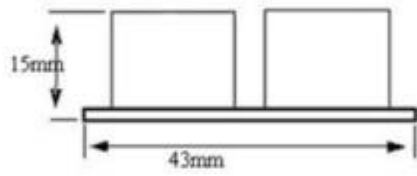
2.0 PACKING LIST

3.0 PRODUCT LAYOUT

VCC = +5VDC

Trig = Trigger input of Sensor Echo = Echo output of Sensor
GND = GND

Practical test of performance,
Best in 30 degree angle

4.0 PRODUCT SPECIFICATION AND LIMITATIONS

| Parameter	Min	Typ.	Max	Unit
Operating Voltage	4.50	5.0	5.5	V
Quiescent Current	1.5	2	2.5	mA
Working Current	10	15	20	mA
Ultrasonic Frequency	-	40	-	kHz

5.0 OPERATION

The timing diagram of HC-SR04 is shown. To start measurement, Trig of SR04 must receive a pulse of high (5V) for at least 10us, this will initiate the sensor will transmit out 8 cycle of ultrasonic burst at 40kHz and wait for the reflected ultrasonic burst. When the sensor detected ultrasonic from receiver, it will set the Echo pin to high (5V) and delay for a period (width) which proportion to distance. To obtain the distance, measure the width (Ton) of Echo pin

Time = Width of Echo pulse, in uS (micro second)

- Distance in centimeters = Time / 58
- Distance in inches = Time / 148
- Or you can utilize the speed of sound, which is 340m/s

Ultrasonic Transducer will issue 8 40kHz pulse
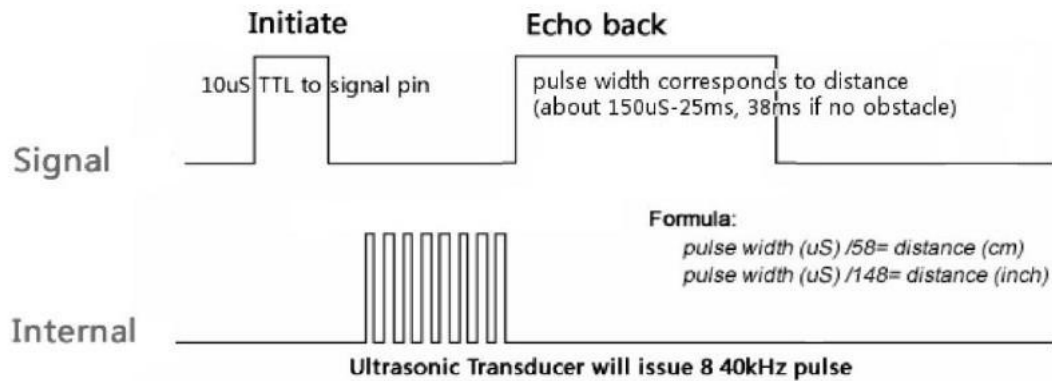
Note:

- Please connect the GND pin first before supplying power to VCC.

- Please make sure the surface of object to be detect should have at least 0.5 meter^2 better performance.

6.0 HARDWARE INTERFACE

Here is example connection for Ultrasonic Ranging module to Arduino UNO board. It can be interface with any microcontroller with digital input such as PIC, SK40C, SK28A, SKds40A, Arduinoseries.
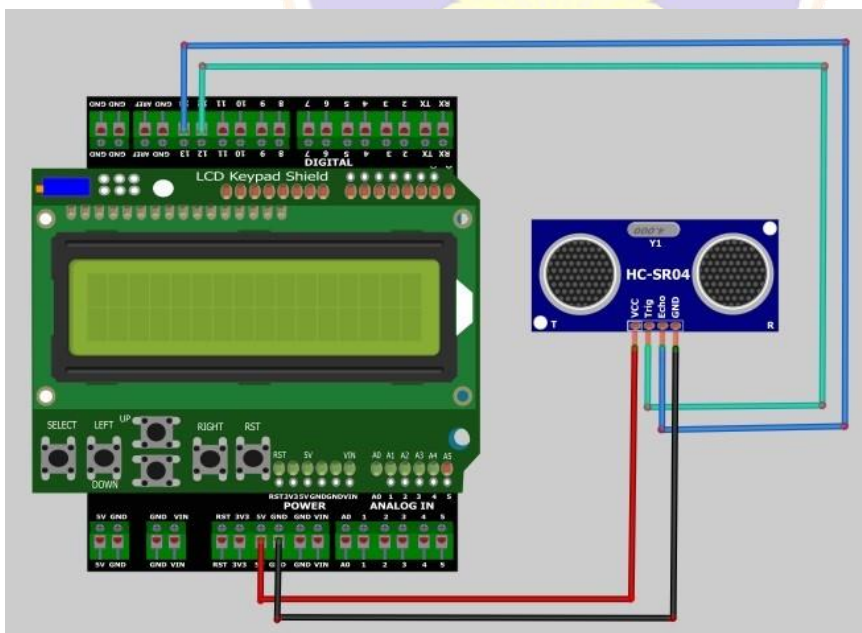
7.0 EXAMPLE CODE

This is examplecode Ultrasonic Ranging module. Please download the complete code at the product page

```
#include "Ultrasonic.h"
#include <LiquidCrystal.h>
LiquidCrystal lcd(8, 9, 4, 5, 6, 7);
Ultrasonic ultrasonic(12,13);

void setup() {
lcd.begin(16, 2);
lcd.setCursor(0, 0);
lcd.print("HC-SR4 testing..");
delay(1000);

}

void loop()
{
  //lcd.clear();
  lcd.setCursor(0, 1);
  lcd.print(ultrasonic.Ranging(CM));
  lcd.print("cm   ");

  delay(100);
}
```
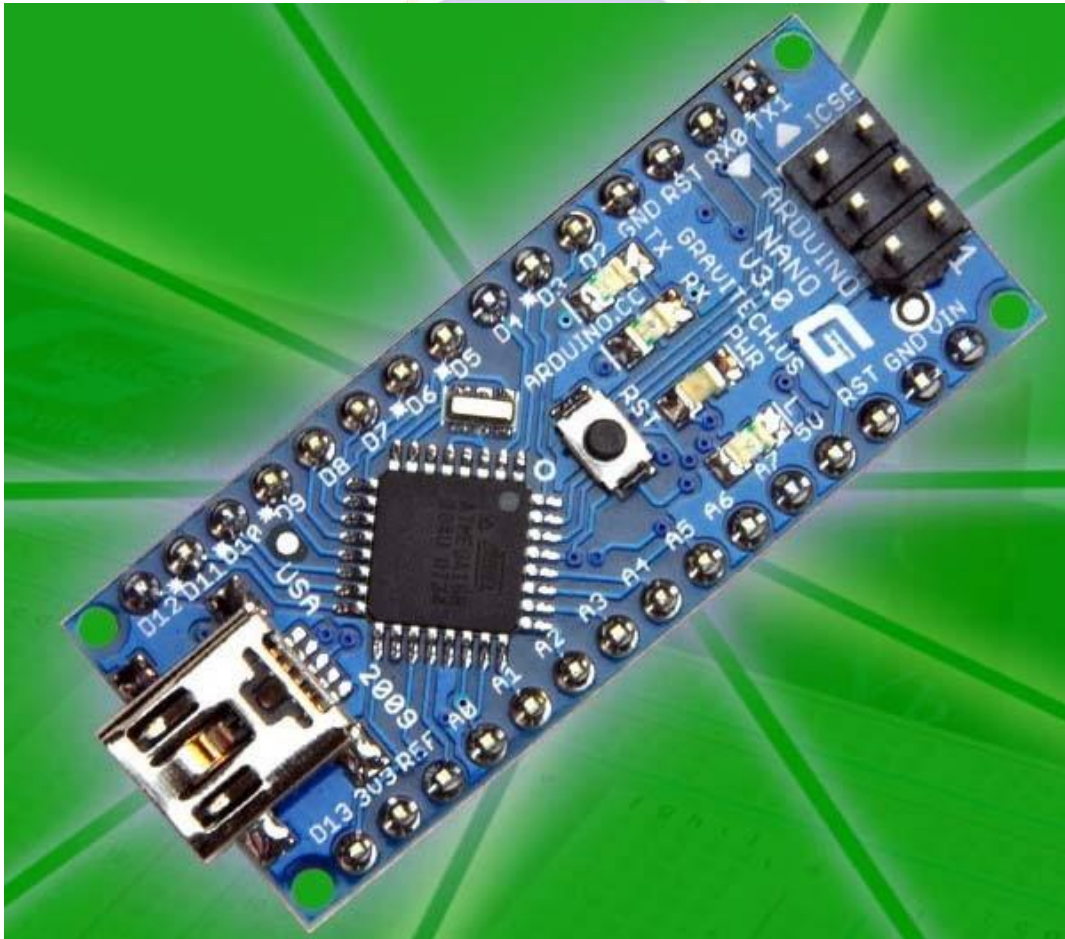
8.0 WARRANTY

- Product warranty is valid for 6 months.

- Warranty only applies to manufacturing defect.

- Damaged caused by miss-use is not covered under warranty
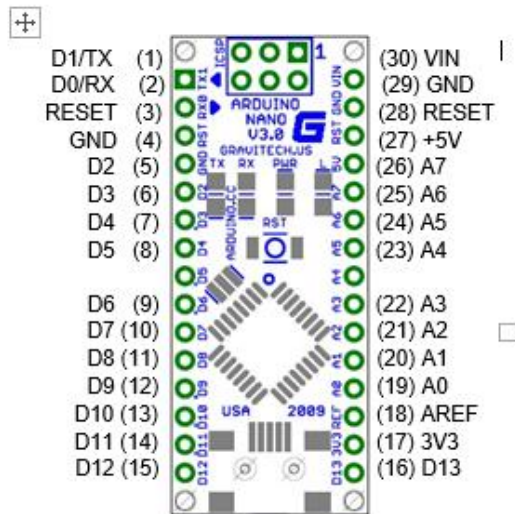
- Warranty does not cover freight cost for both ways.

Arduino Nano

(V3.0)

User Manual

Arduino Nano Pin Layout

Pin No.	Name	Type	Description
1-2, 5-16	D0-D13	I/O	Digital input/output port 0 to 13
3, 28	RESET	Input	Reset (active low)
4, 29	GND	PWR	Supply ground
17	3V3	Output	+3.3V output (from FTDI)
18	AREF	Input	ADC reference
19-26	A0-A7	Input	Analog input channel 0 to 7
27	+5V	Output or Input	+5V output (from on-board regulator) or +5V (input from external power supply)
30	VIN	PWR	Supply voltage

Arduino Nano Mechanical Drawing